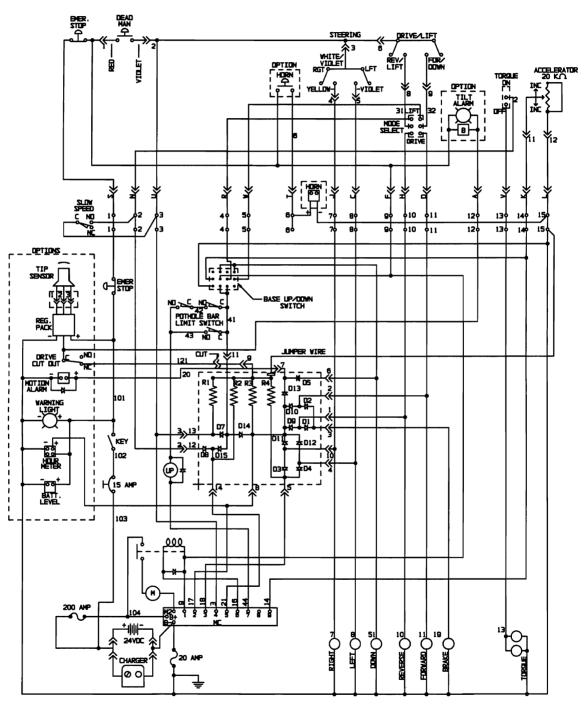


ART515 R0 BM11089

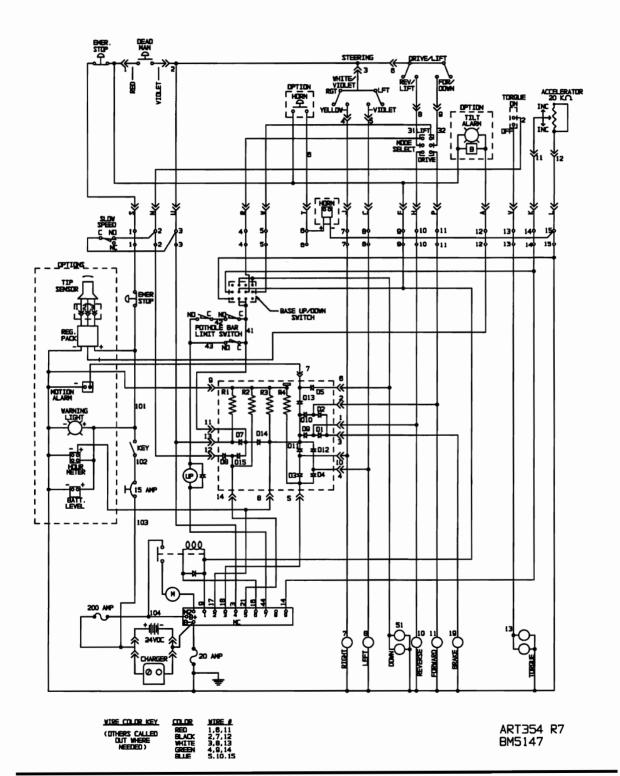
### Figure 2D - Electrical Schematic 2033



SERIAL #8601537-#8601572

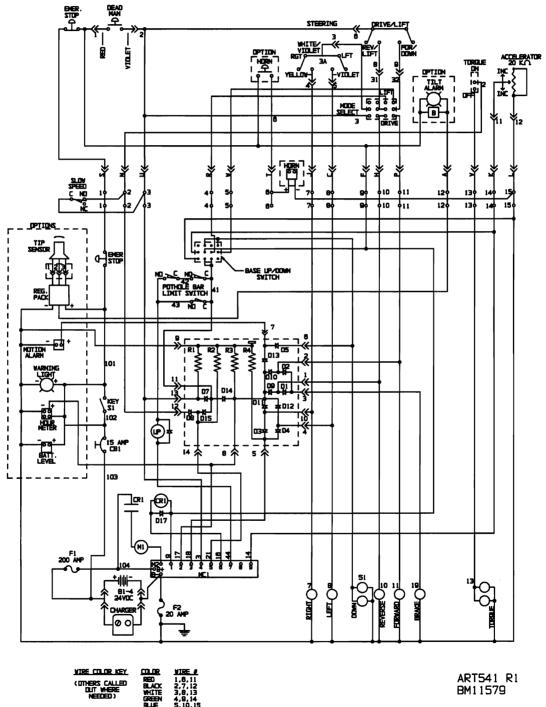
# Figure 2E - Electrical Schematic 2033

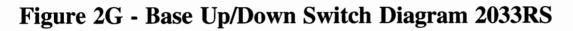
FOR SERIAL #8601573 THROUGH #8602694

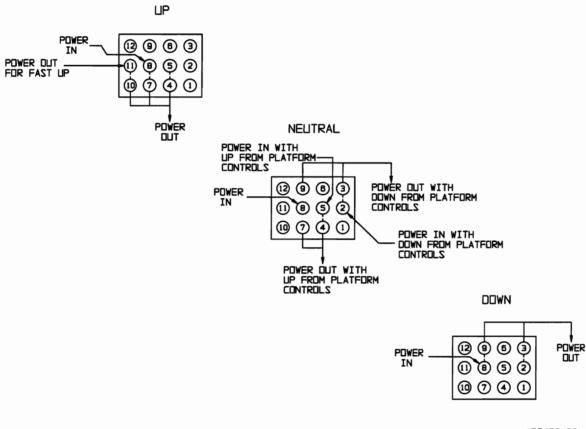


# Figure 2F - Electrical Schematic 2033

FOR SERIAL #8602695 THROUGH PRESENT



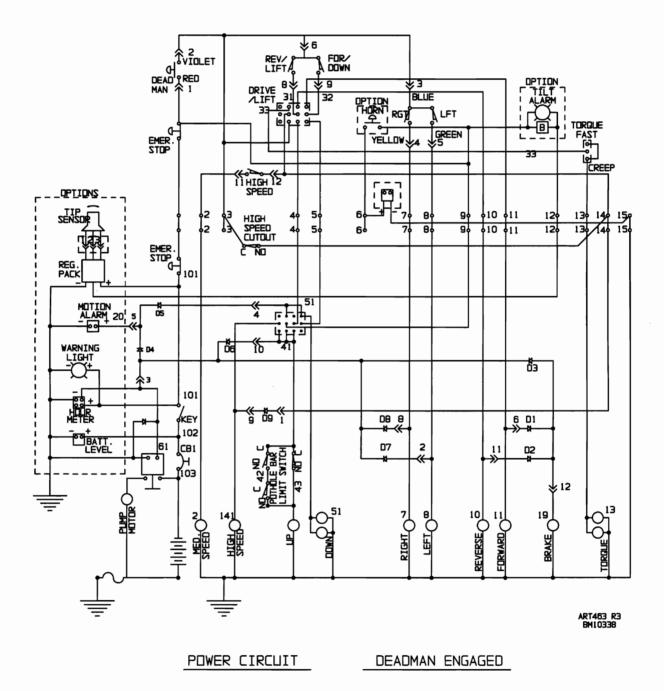




ART468 RO BM10381

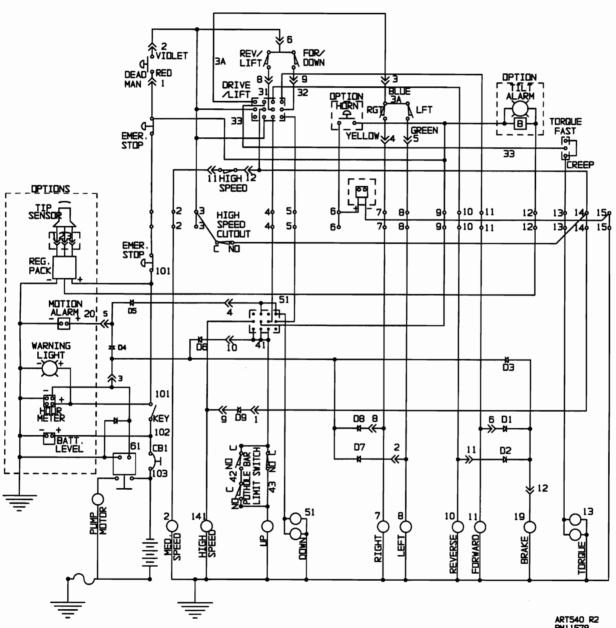
## Figure 2H - Electrical Schematic 2033RS Joystick

FOR SERIAL #8700101 THROUGH 8700646



(MBC)



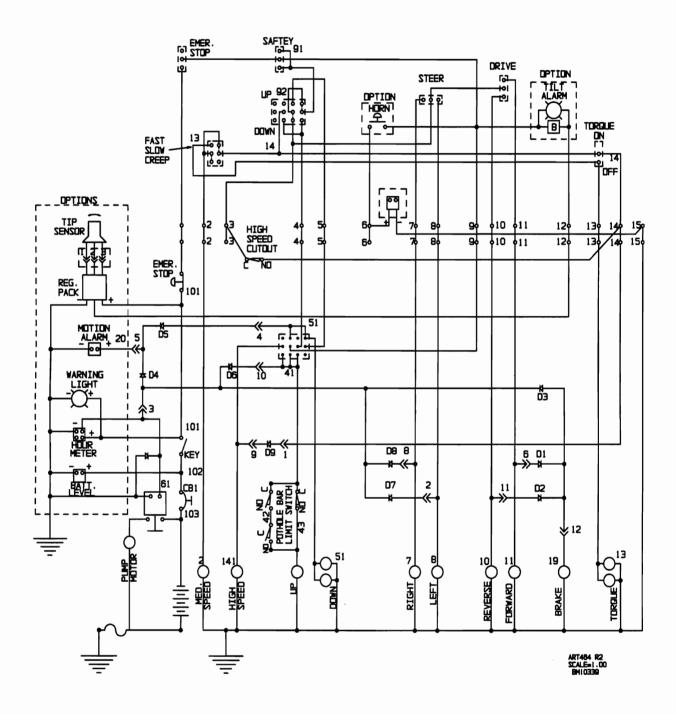


FOR SERIAL #8700647 THROUGH PRESENT

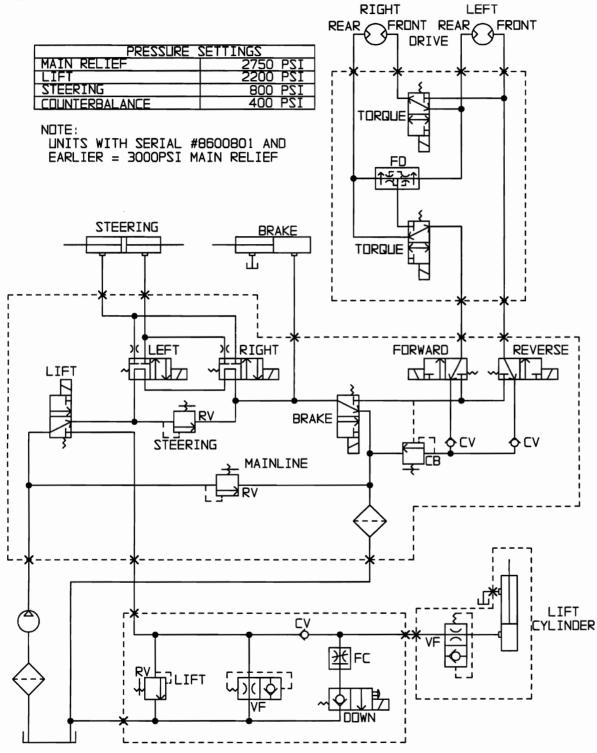
ART540 R2 BM11578 5/17/97



# Figure 2J - Electrical Schematic 2033RS Toggle Box

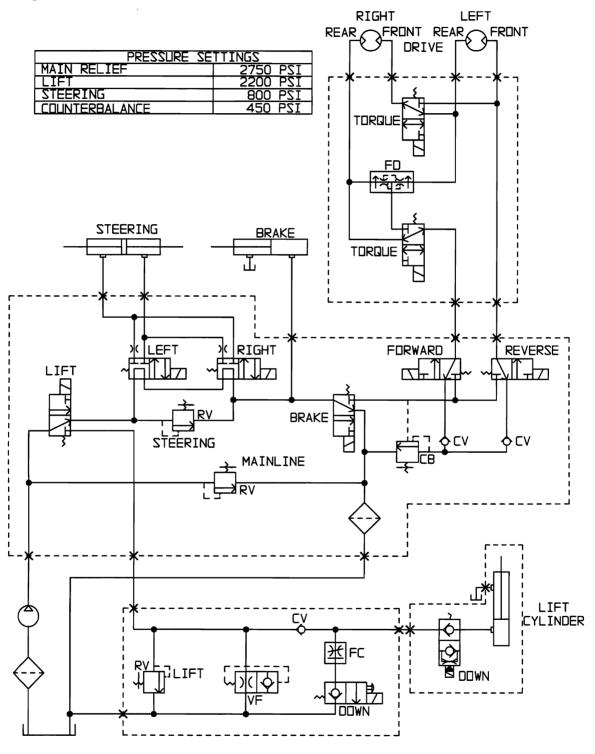


## Figure 2K - Hydraulic Schematic 2033

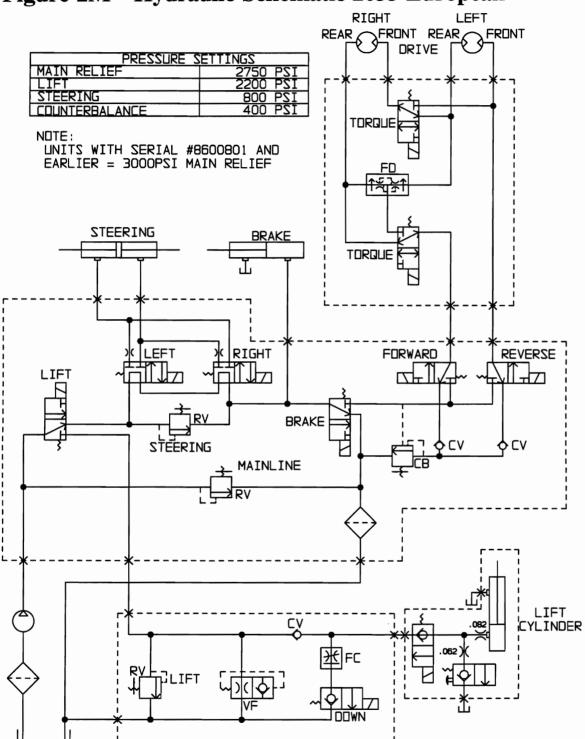


ART370-R6 BM5238

## Figure 2L - Hydraulic Schematic 2033



ART475-R1 BM10367

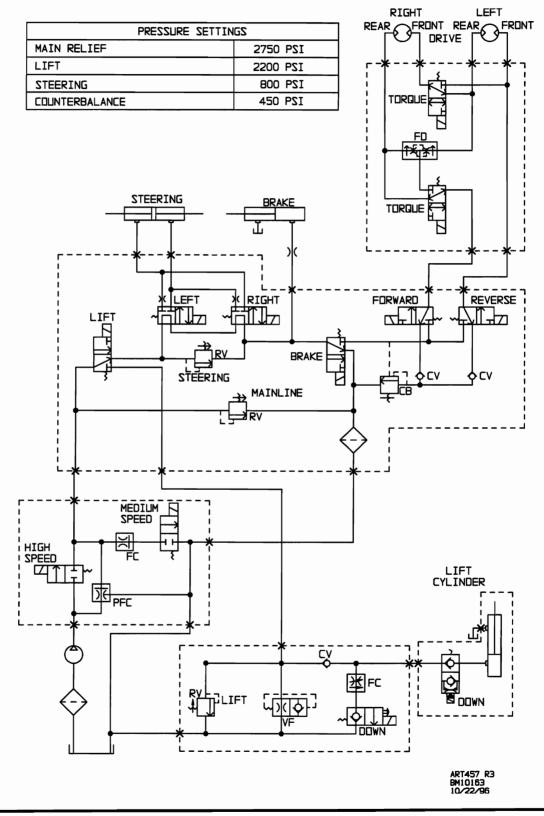


### Figure 2M - Hydraulic Schematic 2033 European

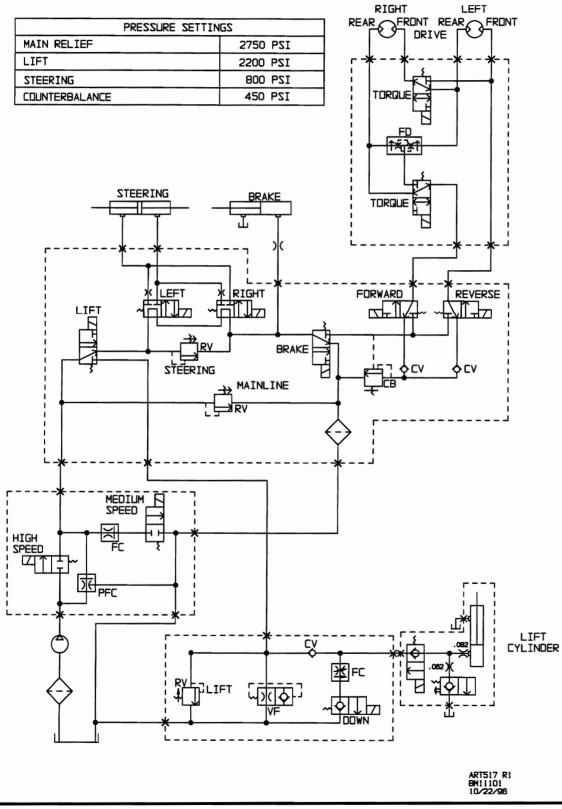
ART477-R2 BM10593

(mec

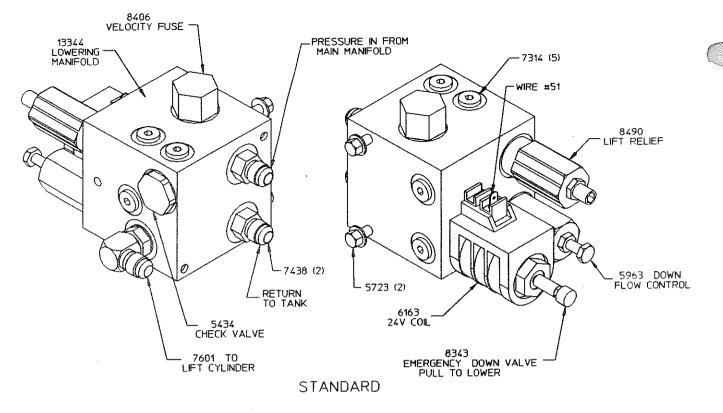
## Figure 2N - Hydraulic Schematic 2033RS



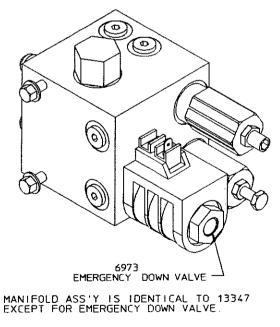
# Figure 2O - Hydraulic Schematic 2033RS



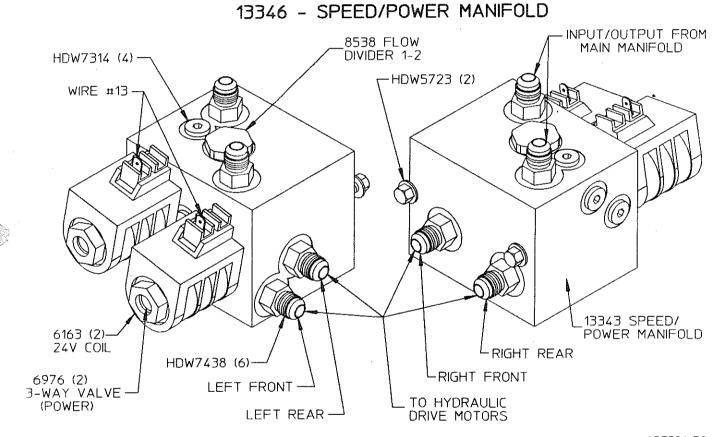
#### 13347 - LOWERING MANIFOLD



13543 - LOWERING MANIFOLD

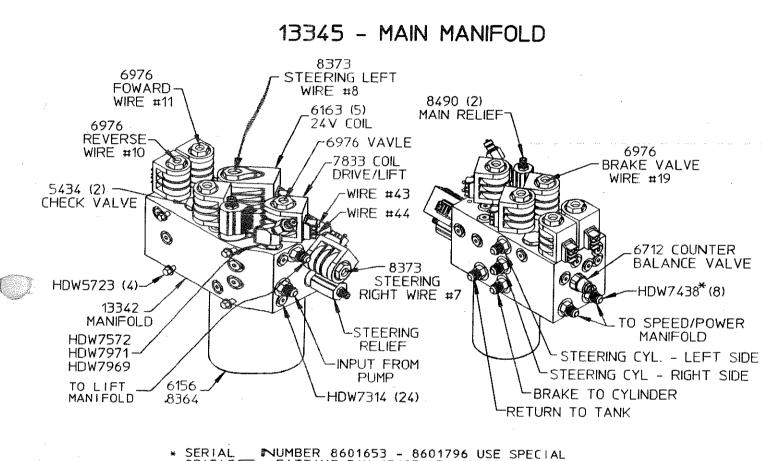


EUROPEAN



ART326-R2 BM4883

Figure 8-6. 2033/2033RS Speed/Power Manifold



SERIAL NUMBER 8601653 - 8601796 USE SPECIAL ORIFICE - FITTING P/N 43685 AT MANIFOLD FOR LEFT STEERING ALL OTHER FITTINGS ARE P/N HDW7438.

40-28813 - Fitting 10526 - Orifice

ART328 BM4885

# 13648-2033RS SPEED MANIFOLD

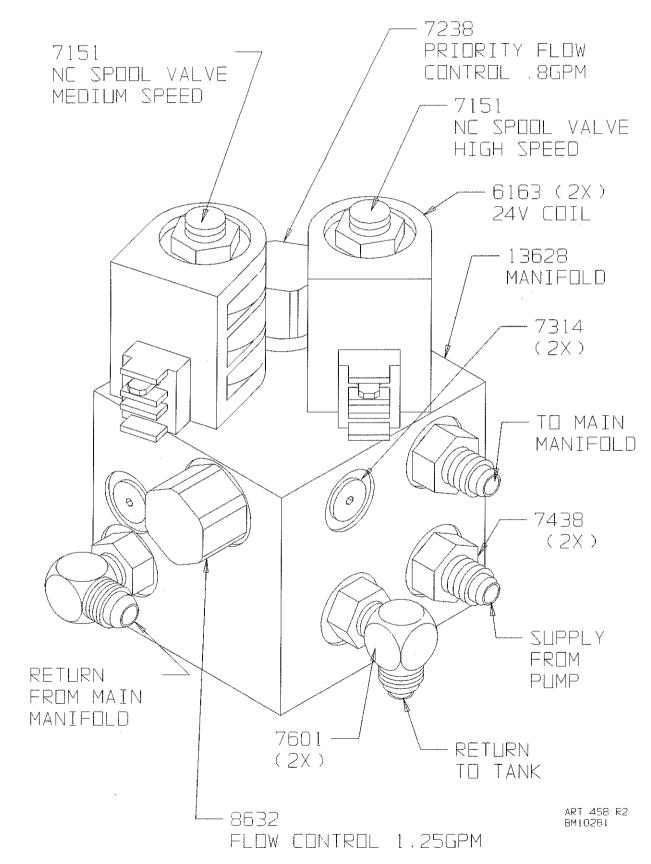
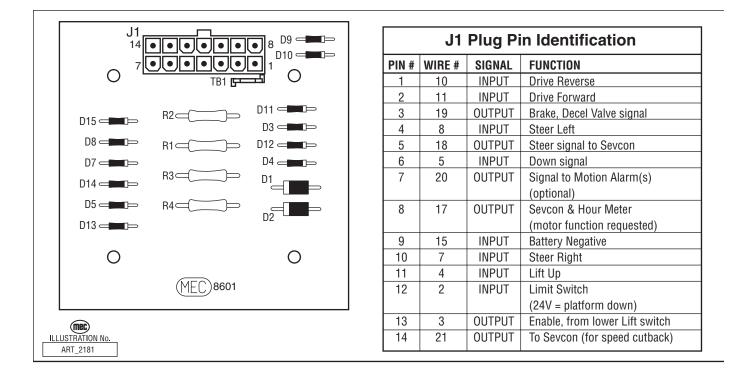


Figure 8-8. 2033RS Speed Manifold

# DIODE BOARD

The diode board is located inside the lower control box.

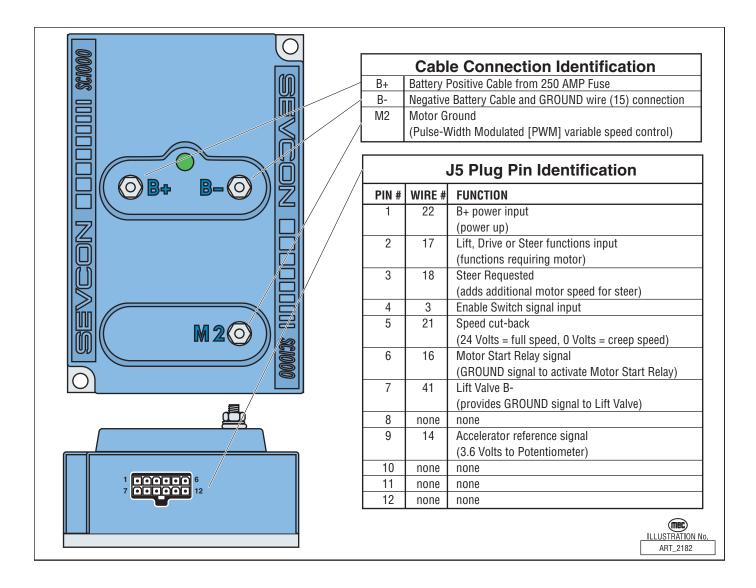




# SEVCON MOTOR SPEED CONTROLLER

The Sevcon Motor Speed Controller (MC-1) is a microprocessor designed with the express purpose of operating the D/C electric motor at varying speeds. The controller uses Pulse-Width Modulation (PWM) technology on the Ground side of the motor to control motor speed. Out of concern for operator safety and to prevent short-circuiting, the Controller monitors certain circuits for potential abnormalities. When the controller senses a problem it errs to the side of safety and stops all motor operation. The green LED will flash a code indicating the reason for the shutdown.

Refer to the *LED Diagnostics Definitions* and *Sevcon Motor Speed Controller - Connections* on the following pages.





### LED Diagnostics Definitions (Flash Codes)

LED READING	DIAGNOSIS
LED Steady On	Controller is operational and detects no irregularities on monitored circuits.
LED Off	<ul> <li>No power-up</li> <li>No power to pin # 1</li> <li>No ground to B- post</li> <li>LED failure or internal controller fault</li> </ul>
2 Flashes	<ul> <li>Procedure fault.</li> <li>Enable depressed at power up</li> <li>Enable depressed for more then 15 seconds without function request</li> <li>No signal on wire 17 pin # 2 when function requested</li> <li>No B- to diode board</li> <li>Failed diode/s</li> <li>Damaged wire harness</li> <li>Internal controller fault</li> </ul>
3 Flashes	<ul> <li>Motor circuit low.</li> <li>Set with unit at rest and is the result of the voltage at M-2 dropping to approximately 4 volts or lower. Possible causes: <ul> <li>Short to ground in the motor circuit between the motor contactor and the M-2 terminal</li> </ul> </li> </ul>
4 Flashes	<ul> <li>Motor circuit high.</li> <li>Set with the unit at rest and is the result of the voltage at M-2 terminal rising above 21 volts. Possible causes:         <ul> <li>Motor contactor points are welded shut</li> </ul> </li> </ul>
5 Flashes	<ul> <li>Motor contactor circuit open.</li> <li>Set when a function is requested but no current can flow through the motor circuit to the M-2 terminal. Possible causes: <ul> <li>Blown 200 amp fuse</li> <li>Malfunctioning motor contactor</li> <li>Worn motor brushes</li> <li>Incomplete circuit to the Sevcon pin #6</li> </ul> </li> <li>If the motor and contactor circuits are diagnosed as working properly: <ul> <li>Sevcon internal fault</li> </ul> </li> </ul>

continued...

LED READING	DIAGNOSIS
6 Flashes	Accelerator fault. Set with unit at rest, a 6 flash will result in an 80% cutback of motor speed. The Accelerator is the proportional control circuitry for the Sevcon. It works in conjunction with the potentiometer located in the upper control box, which is connected to the joystick handle through a gear arrangement.
	<ul> <li>Measure voltage at terminals 14 and 15 on the platform terminal strip or at the potentiometer plug connection.</li> <li>With the joystick handle in neutral, 3.6 volts should be measured on the accelerator circuit (wire #14)</li> <li>Voltage proportionally decreases with the travel of the joystick, with 0 volts at full stroke</li> <li>With the joystick centered, voltages lower than 3.1 or higher than 3.9 will trigger a (6 flash) code</li> </ul>
7 Flashes	<ul> <li>Battery voltage fault.</li> <li>This includes battery voltage below 12 volts or above 45 volts as measured on pin #1</li> <li>This code will disable all functions</li> </ul>
8 Flashes	<ul> <li>Thermal cutback.</li> <li>Sevcon internal temperatures above 176 degrees F</li> <li>Will limit motor speed in comparison with over temperature</li> <li>Resets when cooled</li> </ul>
9 Flashes	<ul> <li>Battery voltage at or below 18 volts</li> <li>As measured on pin #1</li> <li>This code will interrupt or prevent lift function but will allow drive and steer functions</li> <li>When lift is interrupted due to a 9 flash, the electric motor will still run.</li> </ul>



#### **Sevcon Motor Speed Controller - Connections**

The following two pages describe the connections to the Sevcon Motor Speed Controller with a brief description of their function and the voltage measurements under normal conditions.

#### Important:Batteries must be fully charged before troubleshooting! A fully charged battery set on a 24 V DC system will have a nominal

voltage of 25.6 V DC

	-	
FUNCTION	VOLTAGE READING	
PIN 1 - WIRE 22 (Wire 9 on early units)		
Battery Positive Input	Switched	
	<ul><li>5% less than battery voltage</li><li>Controller power-up and reference point for battery state-of-charge</li></ul>	
	Green LED indicates controller power-up	
	<ul> <li>Power travels through the upper emergency-stop switch with upper controls selected</li> </ul>	
	<ul> <li>7-Flash code and 9-flash code indicate low voltage at this terminal</li> </ul>	
Pin 2 Wire 17		
Lift, Drive or	Motorized function is requested	
Steer functions requested	15%-18% less than battery voltage	
Tequesteu	<ul> <li>Controller begins the motor run sequence with this signal but still requires a signal on pin 4 and a change on pin 9 before the motor will operate</li> </ul>	
Pin 3 Wire 18		
Steer Function Requested	When steering is operated	
	<ul> <li>15%-18% less than battery voltage</li> <li>Adds motor speed to compensate for addition of steer requirement during drive operation</li> </ul>	
	<ul> <li>Provides a minimum motor speed for steer requirement when only steer is operated</li> </ul>	
Pin 4 Wire 3		
Enable signal	When joystick trigger pulled	
input	<ul><li>5% less than battery voltage.</li><li>Motor will not start without this input</li></ul>	
	<ul> <li>A signal here longer then 15 seconds without a signal on pin-2 or pin-3 will result in a 2-flash code failure</li> </ul>	
Pin 5 Wire 21		
Speed cut-back	Full speed: 24 V DC	
signal from limit switch or Lift	Creep speed: <b>0 V DC</b> .	
circuit	Speed cut-back is the elevated drive speed	



#### Sevcon Motor Speed Controller - Connections (continued)

FUNCTION	VOLTAGE READING		
PIN 6 – WIRE 16			
Motor Start	Idle: 24 V DC		
Relay ground signal	When function requested: 0 V DC		
	<ul> <li>This is how the Controller maintains control over the motor circuit</li> </ul>		
	<ul> <li>Sevcon controls the Motor Start Relay function ground signal</li> </ul>		
	• Will not operate the motor start relay when 2, 3, 4 & 7 flash codes occur		
PIN 7 – WIRE 41	PIN 7 – WIRE 41		
Ground signal to Lift solenoid valve	0 volts		
	No ground presence until lift is requested		
	<ul> <li>By providing the ground signal, lift function can be prevented anytime battery voltage falls below 18 volts. This will result in a 9 flash code</li> </ul>		
PIN 9 – WIRE 14			
Accelerator reference signal to the	<ul> <li>From 3.5 V DC with joystick in the neutral to 0 V DC at full stroke</li> <li>Controller uses this circuit to monitor joystick input after pins 2 &amp; 4 energize</li> </ul>		
potentiometer (upper control	<ul> <li>Controls motor speed in reference to the voltage on this circuit</li> </ul>		
box)	<ul> <li>Voltages above 4.0 V DC or below 3.0 V DC will result in a 6 flash code</li> </ul>		
POST B+			
Battery positive	Full battery voltage		
cable from 200 amp fuse	No real diagnostic value		
POST B-			
Battery positive	Battery ground cable connection		
cable from 200 amp fuse	Ground path for motor operation		
	<ul> <li>All system ground wires (wire #s 15 &amp; 15A) terminate here</li> </ul>		
	<ul> <li>Best place to connect ground lead from multi-meter while troubleshooting</li> </ul>		
POST M-2			
PWM controlled	Idle: 12 V DC – 13 V DC		
motor ground	During operation, between 5 V DC & 24 V DC		
	<ul> <li>12 – 13 volts is reference voltage used by the controller to monitor motor circuit irregularities at idle</li> </ul>		
	<ul> <li>0 volts at idle = 3 flash code</li> </ul>		
	<ul> <li>Above 20 volts at idle = 4 flash code</li> </ul>		
	<ul> <li>No voltage change after Motor Start Relay signal = 5 flash code</li> </ul>		

